

# This Week's Progress



#### C++ Scripts

- Translating python scripts
- Running C++ scripts within Flutter



#### **ML vs NML**

- MOSSE scripts
- ML detection



#### **Distortion**

- Undistortion of camera lens
- Calibrate-once method

## C++ Scripts

- Translated current Python detection scripts into C++
  - Python scripts are not fully functional
  - Implement OpenCV and camera operations for testing

- Added Flutter capabilities to run C++ scripts on mobile.
  - Can basic cpp "Hello World" files



You have pushed the button this many times:

O

Hello Hello, world!



## **MOSSE Scripts (NML)**

- Minimum Output Sum of Squared Error
- Object tracking using correlation filters to detect patterns and tendencies.
- Create a template and add filters to find an object detection algorithm with the minimum output sum.
- Inconsistent in different lighting. Not as reliable.



### Machine Learning vs Non-Machine Learning

Can adjust the implementation based on the environment

Slower

Customized training models

**Higher Accuracy** 

Machine Learning

Difficult handling of environmental variables

Fast execution

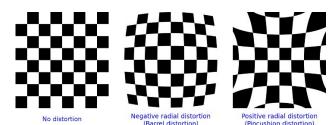
**Less Complex** 

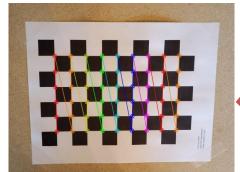
Non-Machine Learning



### **Lens Distortion**

- OpenCV Distortion Detection
  - Uses a checkerboard to find distortive patterns
- Live camera calibration
  - 15 captured photos
  - Side by side display
- File Storage
  - Saves the distortion details locally in a file to be used later.
- Future: Create a CameraManager class to use OpenCV, but automatically undistort with .read()







### **Next Week?**

- Continue translating visual/camera components in C++.
- Integrate calibration techniques into current object detection script.
- Continue testing/prototyping height detection scripts
- Begin Flutter screen development.



